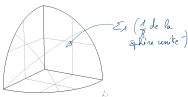


Ex 9

(1)



(2) Ω est la huitième de la boule unité, donc son volume est :

$$V(\Omega) = \frac{1}{8} \cdot \frac{4\pi}{3} = \frac{\pi}{6}$$

(3) $\Sigma = \partial\Omega$, Σ_1 : partie de Σ correspondant à la surface courbe.

$$\Sigma_2 = \Sigma \setminus \Sigma_1$$

$$\vec{f}(x, y, z) = \begin{pmatrix} x^3 \\ y^3 \\ z^3 \end{pmatrix}$$

$$\Sigma_1: \vec{r}_1(\varphi, \theta) = \begin{pmatrix} \sin \varphi \cos \theta \\ \sin \varphi \sin \theta \\ \cos \varphi \end{pmatrix}, (\varphi, \theta) \in [0, \frac{\pi}{2}]^2$$

$$\Phi_1 = \iint_{\Sigma_1} \vec{f} \cdot d\vec{\Sigma} = \int_0^{\pi/2} \int_0^{\pi/2} \vec{f}(\vec{r}_1(\varphi, \theta)) \cdot \left(\frac{\partial \vec{r}_1}{\partial \varphi} \wedge \frac{\partial \vec{r}_1}{\partial \theta} \right) d\varphi d\theta$$

$$\frac{\partial \vec{r}_1}{\partial \varphi} \wedge \frac{\partial \vec{r}_1}{\partial \theta} = \begin{pmatrix} \cos \varphi \cos \theta \\ \cos \varphi \sin \theta \\ -\sin \varphi \end{pmatrix} \wedge \begin{pmatrix} -\sin \varphi \sin \theta \\ \sin \varphi \cos \theta \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} \sin^2 \varphi \sin \theta \\ \sin^2 \varphi \cos \theta \\ \cos^2 \varphi \sin \varphi \end{pmatrix}$$

$$\Phi_1 = \int_0^{\pi/2} \int_0^{\pi/2} \begin{pmatrix} \sin^3 \varphi \cos^2 \theta \\ \sin^3 \varphi \sin^2 \theta \\ \cos^3 \varphi \sin \varphi \end{pmatrix} \cdot \begin{pmatrix} \sin^2 \varphi \cos \theta \\ \sin^2 \varphi \sin \theta \\ \cos^2 \varphi \sin \varphi \end{pmatrix} d\varphi d\theta$$

$$= \int_0^{\pi/2} \int_0^{\pi/2} \frac{\sin^5 \varphi \cos^2 \theta + \sin^5 \varphi \sin^2 \theta + \cos^4 \varphi \sin^2 \varphi}{\sin^2 \varphi (\cos^2 \theta + \sin^2 \theta)} d\varphi d\theta$$

$$= \underbrace{\left(\int_0^{\pi/2} \sin^3 \varphi d\varphi \right)}_{I_2} \cdot \left(\underbrace{\int_0^{\pi/2} \cos^2 \theta d\theta}_{I_3} + \underbrace{\int_0^{\pi/2} \sin^2 \theta d\theta}_{I_4} \right) + \frac{\pi}{2} \cdot \underbrace{\int_0^{\pi/2} \cos^4 \varphi \sin \varphi d\varphi}_{I_4}$$

$$\textcircled{a} I_1 = \left[-\frac{\cos^5 \varphi}{5} \right]_0^{\pi/2} = \frac{1}{5}$$

$$\textcircled{b} I_2 = \int_0^{\pi/2} \sin^5 \varphi d\varphi = \int_0^{\pi/2} (\sin^4 \varphi) \sin \varphi d\varphi = \int_0^{\pi/2} (1 - \cos^2 \varphi) \sin \varphi d\varphi$$

$$\text{on pose } u = \cos \varphi, du = -\sin \varphi d\varphi$$

$$I_2 = - \int_1^0 (1 - u^2) du = \int_0^1 (1 - u^2) du = \int_0^1 1 - 2u^2 + u^4 du$$

$$= 1 - 2 \cdot \frac{1}{3} + \frac{1}{5} = \frac{15 - 10 + 3}{15} = \frac{8}{15}$$

$$\textcircled{c} I_3 = \int_0^{\pi/2} \cos^2 \theta d\theta = \int_0^{\pi/2} (\cos^2 \theta) d\theta = \int_0^{\pi/2} \frac{1}{4} (1 + \cos 2\theta) d\theta$$

$$= \frac{1}{4} \int_0^{\pi/2} 1 + 2\cos 2\theta + \cos^2 2\theta d\theta$$

$$= \frac{1}{4} \left(\frac{\pi}{2} + \left[\sin 2\theta \right]_0^{\pi/2} + \frac{1}{2} \int_0^{\pi/2} (1 + \cos 4\theta) d\theta \right)$$

$$= \frac{\pi}{8} + \frac{1}{8} \cdot \left(\frac{\pi}{2} + \left[\frac{\sin 4\theta}{4} \right]_0^{\pi/2} \right)$$

$$= \frac{\pi}{8} + \frac{\pi}{16} = \frac{3\pi}{16}$$

$$\begin{aligned}
 \textcircled{a} \quad I_4 &= \int_0^{\frac{\pi}{2}} \sin^2 \theta \, d\theta = \int_0^{\frac{\pi}{2}} (\sin^2 \theta) \, d\theta \\
 &= \int_0^{\frac{\pi}{2}} \frac{1}{4} (1 - \cos 2\theta)^2 \, d\theta \\
 &= \frac{1}{4} \int_0^{\frac{\pi}{2}} 1 - 2\cos 2\theta + \cos^2 2\theta \, d\theta \\
 &= \frac{1}{4} \left(\frac{\pi}{2} - \left[\sin 2\theta \right]_0^{\frac{\pi}{2}} + \frac{1}{2} \int_0^{\frac{\pi}{2}} 1 + \cos 4\theta \, d\theta \right) \\
 &= \frac{\pi}{8} + \frac{1}{8} \cdot \frac{\pi}{2} + \frac{1}{2} \left[\frac{\sin 4\theta}{4} \right]_0^{\frac{\pi}{2}} \\
 &= \frac{3\pi}{16}
 \end{aligned}$$

$$\begin{aligned}
 \text{Finalement: } \Phi_1 &= I_2 (I_3 + I_4) + \frac{\pi}{2} I_1 \\
 &= \frac{8}{15} \left(\frac{3\pi}{16} + \frac{3\pi}{16} \right) + \frac{\pi}{2} \cdot \frac{1}{5} \\
 &= \frac{\pi}{5} + \frac{\pi}{10} = \frac{3\pi}{10}
 \end{aligned}$$

$$(4) \quad \Phi_2 = \iint_{\Sigma_2} \vec{g} \cdot d\vec{s} = \iint_{\Sigma} \vec{g} \cdot d\vec{s} - \underbrace{\iint_{\Sigma_1} \vec{g} \cdot d\vec{s}}_{\Phi_1}$$

$$\text{Or: } \iint_{\Sigma} \vec{g} \cdot d\vec{s} = \iiint_{\Omega} \operatorname{div} \vec{g} \cdot dV$$

$$\operatorname{div} \vec{g} = 3x^2 + 3y^2 + 3z^2$$

On paramétrise Σ par:

$$\vec{r}(\rho, \theta, \varphi) = \begin{pmatrix} \rho \sin \varphi \cos \theta \\ \rho \sin \varphi \sin \theta \\ \rho \cos \varphi \end{pmatrix}, \quad \begin{aligned} \rho &\in [0, 1] \\ \theta &\in [0, 2\pi] \\ \varphi &\in [0, \frac{\pi}{2}] \end{aligned}$$

$$|J(\rho, \theta, \varphi)| = \begin{vmatrix} \sin \varphi \cos \theta & -\rho \sin \varphi \sin \theta & \rho \cos \varphi \cos \theta \\ \sin \varphi \sin \theta & \rho \sin \varphi \cos \theta & \rho \cos \varphi \sin \theta \\ \cos \varphi & 0 & -\rho \sin \varphi \end{vmatrix}$$

$$= \cos \varphi (-\rho^2 \cos \varphi \sin^2 \varphi) - \rho \sin \varphi (\rho \sin^2 \varphi)$$

$$= -\rho^2 \sin \varphi (\underbrace{\cos^2 \varphi + \sin^2 \varphi}_{=1})$$

$$\iint_{\Sigma} \vec{g} \cdot d\vec{s} = \int_0^{\frac{\pi}{2}} \int_0^{2\pi} \int_0^1 \underset{\operatorname{div} \vec{g}(\vec{r}(\rho, \theta, \varphi))}{3\rho^2 (-\rho^2 \sin \varphi)} \, d\rho \, d\theta \, d\varphi$$

$$= \frac{3\pi}{2} \cdot \underbrace{[-\cos \varphi]_0^{\frac{\pi}{2}}}_{=1} \cdot \underbrace{\left[\frac{\rho^5}{5} \right]_0^1}_{1/5} = \frac{3\pi}{10}$$

$$\text{Ainsi: } \Phi_2 = \frac{3\pi}{10} - \frac{3\pi}{10} = 0$$

(5) Σ_1 représente $\frac{1}{8}$ de la sphère unité, son aire est donc: $\frac{1}{8} \cdot 4\pi = \frac{\pi}{2}$

(6) Σ_2 représente 3 fois un quart de disque unité, son aire est donc:

$$3 \times \frac{1}{4} \times \pi = \frac{3\pi}{4}$$

(7) $\mathcal{C} = \partial \Sigma_1$

$$\oint_{\mathcal{C}} \vec{g} \cdot d\vec{\ell} = \iint_{\Sigma_1} \operatorname{rot} \vec{g} \cdot d\vec{s} = 0$$

$$\operatorname{rot} \vec{g} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \wedge \begin{pmatrix} x^3 \\ y^3 \\ z^3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$